

# I/O Systems



## Practice Exercises

- 13.1 State three advantages of placing functionality in a device controller, rather than in the kernel. State three disadvantages.
- 13.2 The example of handshaking in Section 13.2 used 2 bits: a busy bit and a command-ready bit. Is it possible to implement this handshaking with only 1 bit? If it is, describe the protocol. If it is not, explain why 1 bit is insufficient.
- 13.3 Why might a system use interrupt-driven I/O to manage a single serial port, but polling I/O to manage a front-end processor, such as a terminal concentrator?
- 13.4 Polling for an I/O completion can waste a large number of CPU cycles if the processor iterates a busy-waiting loop many times before the I/O completes. But if the I/O device is ready for service, polling can be much more efficient than is catching and dispatching an interrupt. Describe a hybrid strategy that combines polling, sleeping, and interrupts for I/O device service. For each of these three strategies (pure polling, pure interrupts, hybrid), describe a computing environment in which that strategy is more efficient than is either of the others.
- 13.5 How does DMA increase system concurrency? How does it complicate hardware design?
- 13.6 Why is it important to scale up system bus and device speeds as the CPU speed increases?
- 13.7 Distinguish between a STREAMS driver and a STREAMS module.

